

REVISIONS

MLC	DESCRIPTION	INC BY	APPROVAL & DATE

APPLICABLE DOCUMENTS

Motor Control PCB Assembly 20217-001


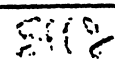
Engineering Specifications:

The HDA components shall meet all requirements and specifications set forth in the following documents unless separately specified herein.

Motor Control PCB (Fab drawing)	20218-001
HDA Assembly drawing	58157-001
HDS Electrical interconnect drawing	
Magnetic Disc	30126-001
Read/Write Heads	30134-001
Head Connector	10420-016
Spindle Motor Connector	10417-006
Stepper Motor Connector	10417-005
Index Connector	10417-005

DWG. NO.

MODEL NO. FIRST USE	ST-412.9	NEXT ASSY FIRST USE	FINAL ASSY
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DRAWN		 <p>SEAGATE TECHNOLOGY</p>
CHECK		
APPD(E)		
APPD(M)	 1.19.81	ST412.9 HEAD DISC ASSEMBLY

UNLESS OTHERWISE SPECIFIED

DIMENSIONS ARE IN INCHES
TOLERANCES ON
DECIMALS ANGLES
.XX ±
.XXX

SCALE	SIZE	DWG NO.	REV. EC
	A	30173-001	0292

Engineering Specification

30173-001

0292

TITLE ST 412.9 HEAD DISC ASM SPECIFICATION
HEAD DISC ASSEMBLY

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APPLICABLE DOCUMENTS (continued)

TK Ø Connector	10417-005
Spin Motor PCB Connector	10419-002
10416-XXX (Ref) Mates with	10417-XXX
10415-XXX (Ref) " "	10420-XXX
10418-XXX (Ref) " "	10419-XXX
Shock & Vibration Spec.	30138-001
Acoustical Specification	30131-001
Shock & Vibration Spec.	30138-001

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I. SCOPE

The Head Disc Assembly (HDA) is a sub-assembly of the ST412.9 Final Disc Drive Assembly. It will undergo all the drive testing before being shipped to the customer. The Head Disc Assembly will be a complete ST412.9 disc drive less the following hardware:

- 1) Main control PCB
- 2) Front panel

II. CAPACITYUnformatted

Mbytes/Drive
Bytes/Track

12.76
10416

Formatted 32 Sectors/Track (Soft)

Mbytes/Drive
Bytes/Track

10.0
8192

<u>Max recording frequency (MHZ)</u>	2.5
<u>Transfer Rate</u>	
Mbits/Second	5.0
<u>Density</u>	
Flux Changes/Inch	9074

III. MEDIA

Tracks

Per Inch	345
Per Surface	306
Per Drive	1224

Defects (Hard Errors)

Per Drive	12
Per Cylinder Zero	0

IV. ENVIRONMENTAL

<u>Ambient Temperature*</u>	<u>Operating</u>	<u>Shipping</u>	<u>Storage</u>
	39° - 135°F 10° - 50	25° - 144°F -4° - 62°C	-8° - 176° -22°C - 80°

<u>Max Temperature Gradient/Hour</u>	18°F	18°F	18°
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<u>Relative Humidity</u>	20 - 80%	TBD	TBD
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<u>Maximum Wet Bulb</u>	78°	No Condensation
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<u>Stray Magnetic Field (1" from casting)</u>	20 Gauss Max
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<u>Altitude</u>	10,000 ft. Max
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* Ambient Temperature is defined as the HDA casting temperature.

V. RELIABILITYError Rate (Excluding defects) - When used with Seagate Technology PCB P/N TBD.Soft read errors (16 retries min.) 1 per 10^{10} bits transferredHard read errors 1 per 10^{12} bits transferredSeek errors 1 per 10^6 seeksMTBF (Meantime before failure)

Typical usage 11,000 hours

PM (Preventive Maintenance) NoneMTR (Meantime to Repair) 30 minutesComponent Life 5 yearsMedia Life 10,000 starts/stopsVI. POWERDC Voltages (To motor speed control)+12 VDC $\pm 10\%$, .3 AMP running current; 2.7 AMPS typical motor start current. (see ST412 manual for start profile).BTU/Hr. (1 watt = 3.413 BTU/Hr.)

Watts	25	$\pm 40\%$
BTU/Hr.	85.3	$\pm 40\%$

VII. INTERFACE

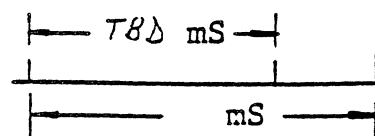
TBD:

VIII. DRIVEA. Mechanical

Seek Settle Time*
Uncontrolled
Controlled

Track to Track
(Seek = 3 ms)

TBD
TBD using this step sequence



* Using Seagate recommended PCB

Engineering Specification

ST412.9 HEAD DISC ASM SPECIFICATION
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Drive Motor Start Time

15 sec.

Spindle Speed**

3600 rpm \pm 1%

HDA Cleanliness

The air inside the HDA shall be class 100 (0.5) micron particles)

Mounting

See Figures 1 & 2

Vibration and Shock

Shall meet the requirements of Seagate Specification 30132-001

B. Electrical

For purposes of normalized test data, and unless otherwise stated, all test measurements shall be taken at the ambient conditions of 68 \pm 5°F (20 \pm 3°C) and 40 to 60% relative humidity after the HDA has been stabilized at the test environment for at least 1 $\frac{1}{2}$ hour.

Notwithstanding this, the HDA shall be capable of meeting all the requirements of this specification over the full operating environment of Paragraph IV, Page 4.

Warm Up Time

The HDA shall meet all operating specifications within 15 seconds after spindle motor has reached 3600 RPM at all operational environmental conditions.

1. Spindle motor speed regulation . 3600 \pm 1% RPM
2. Spindle motor current .

Start	2.75amps max.
Running	1.0 amps max.
3. Stepper motor/phase T8D

**Adjustments are customer responsibility

***For shipment, the heads shall be moved center track while the spindle is rotating.

4. Performance (Head Disc Asm)

Average 2F amplitude 1.0 mv p-p min.

Inside window margin 30 ns total
(without write precomp)Minimum resolution on any track 60%
(without precomp.)Wide Gap Measurement

1. DC erase tracks 303, 304, 305
2. Write 2F on track 304
3. Write 1F on tracks 303 & 305
4. Measure 1F amplitude relative to 2F amplitude on track 151 using H.P. spectrum analyzer Model No. 3585A or equivalent.
5. Failure is defined as a measurement \sum - 26dB.

Engineering Specification

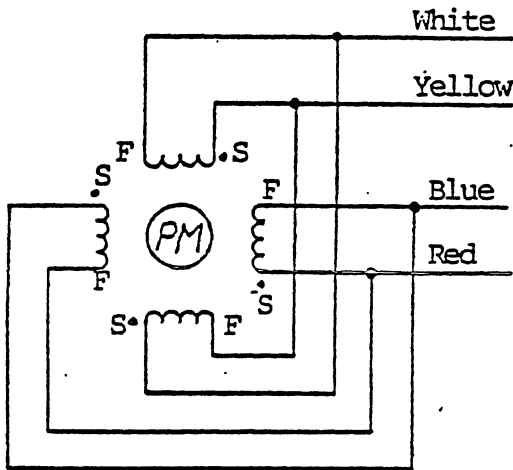
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ST412.9 HEAD DISC ASM SPECIFICATION

TITLE 30173-001

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S: Start F: Finish

ELECTRICAL REQUIREMENTS

STEPPER MOTOR

Switching Sequence for CCW Rotation
Facing Mounting End

Step	Pin 4 Blue	Pin 5 Red	Pin 2 White	Pin 1 Yellow	Pin 3 Not Us
1	-	+	+	-	
2	+	-	+	-	
3	+	-	-	+	
4	-	+	-	+	
5	-	+	+	-	

SCHEMATIC

SPECIFICATIONS	
Step per revolution:	400 (0.9° per step)
Step to step accuracy (Notes 1,2,):	± 6%
Positional Accuracy (1,3):	± 6%
Rotor Inertia:	20 Gcm ² (.28 MOISS)
DC Phase Resistance:	38 ± 3.8 at 25° C
Phase Inductance:	27mH ± 20% at 1 KHZ
Phase Voltage:	9.2
Phase Current (Steady State):	240ma
Holding Torque:	720 gcm (10 oz. - IN) Nom.
Pull-out Torque:	360 gcm (5 oz. - IN) NOM.

NOTES:

1. Measurements made at rated current on each phase.
2. Between any two adjacent step positions.
3. Maximum error in 360°.
4. Motor to be driven bipolar.
The above specifications is of a motor in bipolar mode.
5. Leads: 4, No. 26 AWG PVC insulation UL & CSA approved.

TBD.

Engineering Specification

30173-001

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ST412.9HEAD DISC ASM SPECIFICATION

TITLE 30173-001

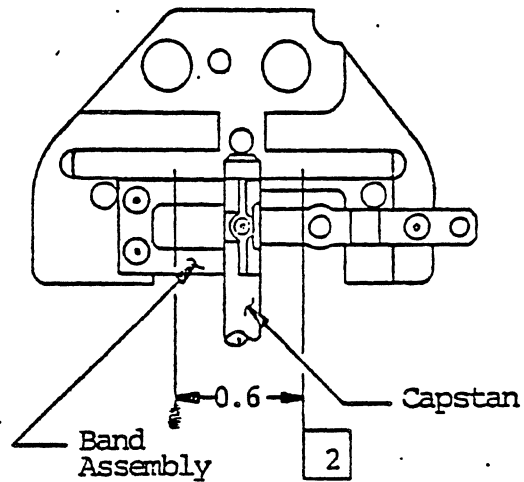
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IX. PHYSICAL REQUIREMENTS

The HDA can be mounted on any side except upside down or front and back. (See Figures 1 & 2)

The HDA is shock mounted for vibration isolation. In the final mounting configuration, care shall be taken to insure that the operation of the three shock mounts is not restricted.

BAND ASSEMBLY



BAND SPECIFICATIONS

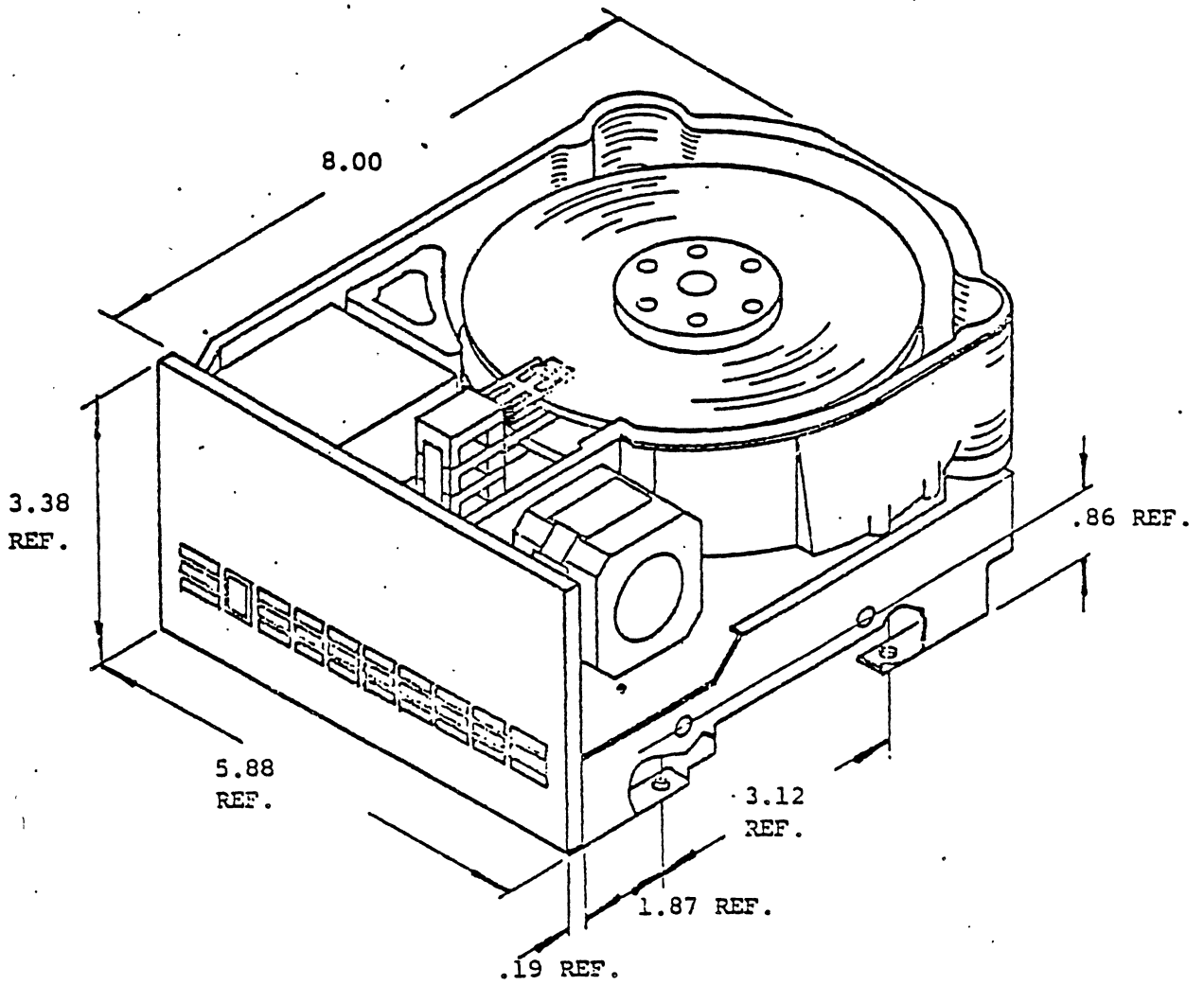
1. Band shall be capable of withstanding 2.5 lbs. Max. tension.
2. There shall be no creases on the active portion of the band.
3. Band shall be free of contaminants that would decrease it's life, such as finger prints and edge nicks.

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TITLE: ST-400 SERIES INTERFACE SPECIFICATION

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TITLE: ST-400 SERIES INTERFACE SPECIFICATION

